On the global Hadamard parametrix in QFT and the signed squared geodesic distance defined in domains larger than convex normal neighborhoods

based on V.M. Letters in Mathematical Physics (2021) 111:130

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Quantum Effects in Gravitational Fields Leipzig University - August 28-September 1 2023

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1. Synge world function and Hadamard parametrix

1.1.1 Relevance in aQFT in CS

- Henceforth (M, g) 4-dim globally hyperbolic spacetime
- The Synge world function aka signed squared geodesical distance $\sigma(x, y)$ appears in the global Hadamard parametrix

$$H_n^T(x,y)_{\epsilon} := \frac{1}{(2\pi)^2} \left(\frac{\Delta(x,y)^{1/2}}{\sigma(x,y)_{\epsilon}^T} + v_n(x,y) \ln \sigma(x,y)_{\epsilon}^T \right)$$

 $\sigma(x, y)_{\epsilon}^{T} := \sigma(x, y) + 2i\epsilon(T(x) - T(y)) + \epsilon^{2}$, T global time function. $\Delta(x, y)$, $v_{n}(x, y)$ (recursively) constructed along the geodesic joining x and y. χ (below) smoothing hat function.

• Let Λ_{ω} be the two-point function of a KG Gaussian state ω ,

$$\Lambda_{\omega}(x,y) - \chi(x,y)H_n^{\mathsf{T}}(x,y)_{0^+}$$
 of class $C^n \,\, orall n \in \mathbb{N}$,

is the geometric definition of Hadamard state made rigorous in [Kay-Wald91], but already introduced in [Fulling-Sweeny-Wald78], [Fulling-Narcowich-Wald81].

1.1.2 Relevance in aQFT in CS REMARKS

- (1) Equivalent (analytic) microlocal definition in terms of WF set [Radzikowski96a] exploited in perturbative renormalization.
- (2) At least **locally**, using smooth cutoffs, a **summed** parametrix H_{∞} exists. The def above is equivalent [Radzikowski96b] to

 $\Lambda_{\omega}(x,y) - H_{\infty}^{T}(x,y)_{0^{+}}$ of class C^{∞} locally

(3) The geometric definition and the parametrix H_n (local or global) has been used, in particular, to establish important theoretical features of Hadamard states [Verch94], in the explicit construction of locally-covariant Wick polynomials also time-ordered [Hollands-Wald01,02] including the stress-energy tensor [VM03,Hollands-Wald05], in quantum energy inequalities [Fewster-Smith08], rigorous treatements of Hawking radiation [Fredenhagen-Haag90][VM-Pinamonti12][Kurpicz-Verch-Pinamonti21], Semiclassical cosmological models [Meda-Pinamont-Siemssen21]. (...)

1.2 Local definition of σ and need for a more global def.

• In general contexts (e.g., heat kernel theory) $\sigma(x, y)$ is defined in a neighborhood of the diagonal of $M \times M$, where (M, g) is a Lorentzian (or Riemannian) manifold with any dimension.

• [Kay-Wald91] H_n defined around the diagonal of $M_{\Sigma} \times M_{\Sigma}$, M_{Σ} globally hyperbolic **sub**-spacetime around a **Cauchy surface** Σ of (M, g). (More details later.)

However

• $\sigma(x, y)$ jointly smooth and well-defined in (geodesically) convex (open) sets $C \ni x, y$

 $\sigma_{C}(x,y) := \pm \left(\int_{0}^{1} \sqrt{\left| g\left(\dot{\gamma}_{xy}^{C}(t), \dot{\gamma}_{xy}^{C}(t) \right) \right|} dt \right)^{2} \quad \text{for} \quad x, y \in C$

• γ_{xy}^{C} : $[0,1] \rightarrow C$ unique geodesic segment in C joining x and y; \pm fixed by the causal character of γ_{xy}^{C} if g is Lorentzian.

• $\sigma_C(x,y) \neq \sigma_{C'}(x,y)$ in general if $x, y \in C \cap C'$.

1.3.1 Issues with $\sigma(x, y)$ and $H_n(x, y)$

 \implies in a neighborhoods \mathcal{N} of $diag(M \times M) := \{(x, x) \mid x \in M\}$

 $\mathcal{N} = \bigcup C_p \times C_p$, C_p convex neighborhood of p D∈M

 $\sigma(x, y) := \sigma_{C_p}(x, y)$ for $C_p \ni x, y \Rightarrow$ multivalued in general! N.B. Same problem for Δ and v_n .

• If (M, g) is Riemannian, let every C_p in \mathcal{C} be a geodesic ball centered on $p \in M$, normal neighborhood of p, $\implies \sigma(x, y) := \sigma_{C_x}(x, y)$ is well defined, $= \sigma_{C_y}(x, y)$, jointly smooth on \mathcal{C} , and $\sigma(x, y) = dist_{\sigma}(x, y)^2$ $(dist_{\sigma}(x, y) := \inf\{L_{\sigma}(\gamma) \mid \gamma \text{ joins } x \text{ and } y \text{ in } M\})$ (PROOF: absolute length-minimizing property of geodesic in small geod balls, joint continuity of $dist_{g}$, smoothness of $(exp_{x})^{-1}$, and Sobolev's lemma)

N.B. No Lorentzian generalisation: analog of *dist_g* different properties.

1.3.2 Issues with $\sigma(x, y)$ and $H_n(x, y)$

[Kay-Wald91] σ (and thus H_n) defined in a causal normal neighborhood M_Σ of a Cauchy surface Σ of (M,g), i.e.,
(a) (M_Σ, g|_{MΣ}) globally hyperbolic spacetime,
(b) x, y ∈ M_Σ causally related in M if and only if the causal double-cone J_M(x, y) ⊂ C_{x,y} convex neighborhood .

 \implies If $x, y \in C_{x,y}, C'_{x,y}$ then every **causal** geodesic joining them stays in **both** convex neighborhoods and thus it is **unique**:

 $\sigma(x,y) := \sigma_{C_{x,y}}(x,y)$ with $C_{x,y} \supset J_M(x,y)$ well defined

• However $\sigma(x, y)$, Δ , v_n appearing in $H_n(x, y)$ are assumed and used to be well defined and smooth in a neighborhood \bigcirc of the subset of the causally related pairs in $M_{\Sigma} \times M_{\Sigma}$: there are also causally separated points in \bigcirc .

are $\sigma(x, y)$, Δ , v_n well defined and smooth?

N.B. Problem mainly of mathematical nature: physics uses causal curves only.

2. A topological argument to fix the problem

2.1 Strongly convex neighborhoods

N.B. Better to stay **as close as possible** to the original construction to preserve relevant consequences of that definition accumulated over the years.

BASIC IDEA [VM21] (Other ideas by Sánchez and Gérard) : A covering C of (M, g) made of geodesical convex neighborhoods is strongly convex if

 $C \cap C'$ is geodesically convex for $C, C' \in \mathfrak{C}$

⇒ If $\mathcal{C} \ni C, C' \ni x, y$ then $\sigma_C(x, y) = \sigma_{C'}(x, y)$, because there is **only one** geodesic joining x and y in $C \cap C'$.

⇒ Take $\mathcal{C} := \{C_p\}_{p \in M}$ strongly convex and consider the neighborhood of $diag(M \times M)$ of the form $\mathcal{N} = \bigcup_{p \in M} C_p \times C_p$ ⇒ $\sigma(x, y) := \sigma_{C_p}(x, y)$ for $C_p \ni x, y$ well defined and smooth (as locally smooth) on the whole \mathcal{N} (same result for Δ and v_n).

QUESTION: Do strongly convex coverings exist?

2.2 A crucial property of paracompachtess

• A.H. Stone's result ('49)

THEOREM A topological space X is **Hausdorff** and **paracompact** if and only if it is **T1** and every open covering \mathcal{C} of X admits a *-refinement: another open covering \mathcal{C}^* such that, if $V \in \mathcal{C}^*$,

 $\bigcup \{V' \in \mathbb{C}^* \mid V' \cap V \neq \emptyset\} \subset U_V \quad \text{for some } U_V \in \mathbb{C}.$

• Useful consequence [VM21] since (M, g) is parcompact by definition.

PROPOSITION. If A is an open covering of (M, g) (Riemannian or Lorentzian) there is a refinement C of A (i.e., if $C \in C$, then $C \subset U_C \in A$) that is a strongly convex covering of M.

IDEA OF PROOF. \mathcal{C}_0 made of convex neighborhoods **subsets** of elements of \mathcal{A} . Pass to the *-refinement \mathcal{C}_0^* . \mathcal{C} made of convex neighborhoods **subsets** of elements of \mathcal{C}_0^* . $C, C' \in \mathcal{C}$ convex and (if $C' \cap C \neq \emptyset$) $C' \cap C \subset C'' \in \mathcal{C}_0$ convex as well $\Rightarrow C \cap C'$, convex.

2.3 σ and H_n defined around the diagonal of $M \times M$ PROPOSITION [VM21] Consider the neighborhood $\mathcal{N}_{\mathfrak{C}} = \bigcup_{p \in M} C_p \times C_p$ of diag $(M \times M)$ where $\mathfrak{C} := \{C_p\}_{p \in M}$ is *s*-convex.

(a) The extension

$$\sigma_{\mathbb{C}}(x,y) := \sigma_{C_p}(x,y)$$
 for $C_p \ni x, y$

is well defined and smooth on $\mathcal{N}_{\mathcal{C}}$. The same is true for the associated $H_n^{(\mathcal{C})}$.

(b) If analogous definitions are given for another choice of the s-convex covering \mathcal{C}' , then there is a third s-convex covering \mathcal{C}'' such that $\mathcal{N}_{\mathcal{C}} \cap \mathcal{N}_{\mathcal{C}'} \subset \mathcal{N}_{\mathcal{C}''}$ and

$$\sigma_{\mathcal{C}}|_{\mathcal{N}_{\mathcal{C}}''} = \sigma_{\mathcal{C}'}|_{\mathcal{N}_{\mathcal{C}}''}, \quad H_n^{\mathcal{T},\mathcal{C}}|_{\mathcal{N}_{\mathcal{C}}''} = H_n^{\mathcal{T},\mathcal{C}'}|_{\mathcal{N}_{\mathcal{C}}''}$$

(\mathcal{C}'' made of the geodesically convex neighborhoods included in the intersections of the elements of \mathcal{C} and \mathcal{C}')

3. A slight mathematical change in the geometric definition of Hadamard state

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3.1 Causal normal neighborhoods and parametrices The definition of Hadamard state in [Kay-Wald91] can be fixed, **preserving all results established therein**, through a slight change in the definition of **causal normal neighborhood** of a Cauchy surface

DEFINITION A causal normal neighborhood M_{Σ}^{e} of a spacelike smooth Cauchy surface Σ of (M, g) subordinated to a strongly convex covering \mathcal{C} of M is an open neighborhood of Σ such that (a) $(M_{\Sigma}^{e}, g|_{M_{\Sigma}})$ globally hyperbolic spacetime (with Σ itself as a Cauchy surface)

(b) x, y ∈ M^C_Σ causally related if and only if the causal double-cone J_M(x, y) ⊂ C_{x,y} ∈ C.

N.B. Neighborhoods $M_{\Sigma}^{\mathcal{C}}$ exist for every Σ and \mathcal{C} : direct re-adaptation of the existence proof in [Kay-Wald91].

3.2.1 Geometric definition of Hadamard state

Let us review the geometric definition of Hadamard state according to the change above and following [Kay-Wald91] for a two-point function Λ_{ω} .

- (1) Choose Σ , \mathcal{C} and $M_{\Sigma}^{\mathcal{C}}$ as above.
- (2) In $M_{\Sigma}^{\mathcal{C}}$, define $\sigma_{\mathcal{C}}$ and the associated parametrix $H_n^{T,\mathcal{C}}$ (under the choice of a global temporal function T).
- (3) Choose a smooth function $\chi: M_{\Sigma}^{\mathcal{C}} \times M_{\Sigma}^{\mathcal{C}} \to [0, 1]$ with $\chi = 1$ on the **causally connected pairs** (x, y) and which smoothly vanishes outside that set.

DEFINITION ω is Hadamard if

 $\Lambda_{\omega}(x,y) - \chi(x,y)H_n^{\mathcal{T},\mathbb{C}}(x,y)_{0^+}$ is $C^n \,\,\forall n \in \mathbb{N} \,, x,y \in M_{\Sigma}^{\mathbb{C}}$

The only change is the definition of M_{Σ} that now depends on \mathcal{C} .

3.2.2 Geometric definition of Hadamard state REMARKS.

(1) If $H_n^{T,e}$ and $H_n^{T,e'}$ are two parametrices referred to the same Cauchy surface Σ , but **different** strongly convex coverings, in principle $\sigma_e \neq \sigma_{e'}$ by construction, however

 $\sigma_{\mathfrak{C}}(x,y) = \sigma_{\mathfrak{C}'}(x,y), \quad v_n^{\mathfrak{C}}(x,y) = v_n^{\mathfrak{C}'}(x,y)$

 $H_n^{T,\mathcal{C}}(x,y)_{\epsilon} = H_n^{T,\mathcal{C}'}(x,y)_{\epsilon}$

when $(x, y) \in (M_{\Sigma}^{\mathbb{C}} \times M_{\Sigma}^{\mathbb{C}}) \cap (M_{\Sigma}^{\mathbb{C}'} \times M_{\Sigma}^{\mathbb{C}'})$ are causally related as physically espected.

That is because **causal geodesics** used to compute $\sigma_{\mathcal{C}}$ and $\sigma_{\mathcal{C}'}$ are however the **same**, due to the definition of **causal** normal neighborhood.

(2) The definition of Hadamard state is again independent of the choices of Σ, C, T, χ (same proofs as in [Kay-Wald91] with direct adaptations).

3.3.1 Relation with Radzikowski's micro-local definition

• Microlocal definition of Hadamard state: the 2-point function $\Lambda_{\omega} \in \mathcal{D}'(M \times M)$ satisfies the microlocal spectral condition $WF(\Lambda_{\omega}) =$

 $\{((x_1, k_1), (x_2, k_2)) \in T^*M \setminus 0 \times T^*M \setminus 0 | (x_1, k_1), (x_2, -k_2), k_1 \triangleright 0\}$

Radzikoski's crucial results [Radzikowski96a,b]:

• THEOREM1 Assume that, mod C^{∞} ,

(1) $\Lambda_{\omega} \in \mathcal{D}'(M \times M)$

(2) the antisymmetric part is i/2 times the causal propagator; (3) Λ_{ω} solves the KG equation.

Then the geometric definition of Hadamard state for ω and the microlocal one, are equivalent.

• **THEOREM2** Assuming (1) and (2), the microlocal condition is equivalent to the condition

 $\Lambda_{\omega}(x,y) - H_{\infty}^{T}(x,y)_{0^{+}}$ of class C^{∞}

in a convex neighborhood of every point.

3.3.2 Relation with Radzikowski's micro-local definition QUESTION: Is Theorem 1 valid, taking the changes in the geometric definition of Hadamard state into account?

- Radzikowski's proof of Theorem1 relies upon three facts:
- (a) standard structure of H_n ;
- (b) *T* independence of the geometric definition;
- (c) functions σ , Δ , v_n well-defined and smooth and, in a neighborhood of every point for normal coordinates centered on p, $\sigma(p,q) = -(x(q)^0)^2 + \sum_{k=1}^3 (x^k(q))^2$

• These conditions are guaranteed, so Theorem 1 is true. Theorem 2 uses only the microlocal definition so that it is true as well.

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• As physically expected, the geometric definition of Hadamard state can be made completely consistent by means of a slight change in is te original definition, however based on a general topological result. (However other mathematical approaches possible.)

• The fundamental mathematical tool is the Hadamard parametrix that is well defined in a neighborhood of the diagonal of the spacetime and, in the very definition of Hadamard state, in a certain sub-spacetime constructed around any Cauchy surface.

• Dealing with these technical notions, also in view of various and annoying technical subltelties that one would like to fix once and for all, some natural questions pop up.

Q1 Is it possible to extend parametrices to the whole spacetime?

Q2 Does an assigment of such extensions exists that **respects causal embeddings** of glob. hyp. spacetimes?

Regarding states (in place of parametrix) the answer to Q2 is negative. It is well known that no canonical assignment of (Hadamard Gaussian) states is possible that respects the causal embeddings of globally hyperbolic spacetimes and assigns the standard Minkowski vacuum to the Minkowski spacetime when the time-slice axiom is assumed.

However parametrices are constructed with **local procedures** so that some hope of positive answers exist.

I do not have a definite answer but just some clues. Disreagarding ${\cal T}$ and $\epsilon:$

$$H_n(x,y) := \frac{1}{(2\pi)^2} \left(\frac{\Delta(x,y)^{1/2}}{\sigma(x,y)} + v_n(x,y) \ln \sigma(x,y) \right)$$

Two of the three objects, $\Delta(x, y)$, $\sigma(x, y)$, $v_n(x, y)$ are restrictions of **globally defined** objects when x and y are **causally related** (thus where physics matters).

(1) In strongly causal spacetimes (thus globally hyperblic in particular) $\sigma(x, y)$ is the restriction to convex neighborhoods of the (continuous symmetric) Lorentzian distance

 $\tau(x, y) = -\sup\{L_g(\gamma) | \gamma \text{ is causal and joins } x \text{ and } y \text{ in any order} \}$

(2) v_n(x, y) is (up to constant universal factors) the "restriction" to convex neighborhoods of the kernel of the causal propagator E(x, y). More precisely
 [Thm4.5.1:Friendlander75]

 $\frac{E(x,y) - v_n(x,y)}{\sigma(x,y)^n} \to 0 \quad \forall n \in \mathbb{N} \text{ and } x, y \text{ timelike related}$

and the function E(x, y) computed for $\sigma(x, y) < 0$, continuously extends to a smooth function $E_0(x, y)$ up to $\sigma(x, y) = 0.$

For causally reated x, y in the whole spacetime M, we can write

$$H_n^{\mathsf{T}}(x,y)_{\epsilon} := \frac{1}{(2\pi)^2} \left(\frac{???(x,y)}{\tau^{\mathsf{T}}(x,y)_{\epsilon}} + E_0(x,y) \ln \tau^{\mathsf{T}}(x,y)_{\epsilon} \right)$$

Apparently, this attempt of global definition respects causal embeddings of spacetimes by construction (also T has to be handled).

However I do not know if a **global extesion** of Δ exists. A number of (also subtle) details need to be fixed, first of all how to deal with **spacelike related** arguments.

Many thanks for your attention!