

Benchmarking effective actions and their flow equations in zero dimensions

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Thanks

This talk is based on:

Garbrecht & PM '16 (1509.07847)

Alexander, PM, Nursey & Saffin '19 (1907.06503)

PM & Saffin '19, '21 and '22 (1905.09674, 2107.12914, 2206.08865)

Thanks go to:

- my **wonderful collaborators** in this area,
- the **organisers of ERG2020**, and to **Dario Benedetti, Kevin Falls, Jan Pawlowski** and **Adam Rancon** for the discussions that followed,
- the **organisers of this super meeting**,
- and **all of you** for coming along to this talk.

nPI quantum effective actions (à la Routh)

For each **non-connected n -point correlation function** $\Delta_{x_1, x_2, \dots, x_n}^{\text{nc}}$ of the theory of a scalar field Φ with classical action $S[\Phi]$, we can introduce a function J_{x_1, x_2, \dots, x_n} and define a functional

$$\Gamma_{n, \{J\}}[\{\Delta^{\text{nc}}\}] = W_n[\{J\}] + J_{x_1} \Delta_{x_1}^{\text{nc}} + J_{x_1, x_2} \Delta_{x_1, x_2}^{\text{nc}} + \dots + J_{x_1, x_2, \dots, x_n} \Delta_{x_1, x_2, \dots, x_n}^{\text{nc}}$$

$$W_n[\{J\}] = -\hbar \ln \int D\Phi \exp \left[-\frac{1}{\hbar} \left(S[\Phi] - J_{x_1} \Phi_{x_1} - J_{x_1, x_2} \Phi_{x_1} \Phi_{x_2} - \dots - J_{x_1, x_2, \dots, x_n} \Phi_{x_1} \Phi_{x_2} \dots \Phi_{x_n} \right) \right]$$

Extremizing wrt **all** of the J 's for a given n leads to the **n -particle irreducible effective actions**.

Extremizing wrt a **subset** of the J 's for a given n leads to ... **something else**.

1PI average [Wetterich '91]

The **1PI average effective action** amounts to taking

$$\Gamma_{2, \{J\}}[\{\Delta^{\text{nc}}\}] = W_2[\{J\}] + J_{x_1} \Delta_{x_1}^{\text{nc}} + J_{x_1, x_2} \Delta_{x_1, x_2}^{\text{nc}}$$

- extremizing wrt J_{x_1} only, which sets $J_{x_1} = J_{x_1}[\phi]$ and $\Delta_{x_1}^{\text{nc}} = \phi_{x_1}[\{J\}] = -\delta W_2[\{J\}]/\delta J_{x_1}$,
- setting $\Delta_{x_1, x_2}^{\text{nc}} = \phi_{x_1} \phi_{x_2}$, which sets $\delta \Gamma_{2, \{J\}}[\{\Delta\}]/\delta J_{x_1, x_2} \neq 0$,
- taking $J_{x_1, x_2} = -R_{k; x_1, x_2}/2$ to be proportional to the inverse FT $R_{k; x_1, x_2}$ of the regulator $R_{k; q}$.

2PIreg [Alexander, PM, Nursey, Saffin '19; see also Garbrecht & PM '16]

Instead, let's again take

$$\Gamma_{2, \{J\}}[\{\Delta^{\text{nc}}\}] = W_2[\{J\}] + J_{x_1} \Delta_{x_1}^{\text{nc}} + J_{x_1, x_2} \Delta_{x_1, x_2}^{\text{nc}}$$

- extremize wrt J_{x_1} and J_{x_1, x_2} , which sets $\{J\} = \{J\}[\phi_{x_1}, \Delta_{x_1, x_2}]$,

$$\Delta_{x_1}^{\text{nc}} = \phi_{x_1}[\{J\}] = -\delta W_2[\{J\}]/\delta J_{x_1},$$

$$\Delta_{x_1, x_2}^{\text{nc}} = \hbar \Delta_{x_1, x_2}[\{J\}] + \phi_{x_1} \phi_{x_2} = -\delta W_2[\{J\}]/\delta J_{x_1, x_2},$$

- take $J_{x_1, x_2} = -R_{k; x_1, x_2}/2$ to be proportional to the inverse FT $R_{k; x_1, x_2}$ of the regulator $R_{k; q}$.
[cf. Reinosa's talk on Tuesday, i.e., Blaizot, Pawłowski and Reinosa '11 & '21 and Reinosa '21]

Flow equations

1PI_{average} [Wetterich '93, Morris '94, Ellwanger '94]

Natural variables:

$$\Gamma_{\text{av}}^{1\text{PI}} = \Gamma_{\text{av}}^{1\text{PI}}[\phi, R_k]$$

Fix $J_{x_1} = J_{k; x_1}$ such that $\partial_k \phi = 0$ and then

$$\partial_k \Gamma_{\text{av}}^{1\text{PI}} = \frac{\delta \Gamma_{\text{av}}^{1\text{PI}}}{\delta R_k} \cdot \partial_k R_k = \frac{\hbar}{2} \Delta_k^{1\text{PI}} \cdot \partial_k R_k$$

by the functional chain rule.

2PI_{reg} [Alexander, PM, Nursey, Saffin '19]

Natural variables:

$$\Gamma_{\text{reg}}^{2\text{PI}} = \Gamma_{\text{reg}}^{2\text{PI}}[\phi, \Delta_k]$$

Fix $J_{x_1} = J_{k; x_1}$ such that $\partial_k \phi = 0$ and then

$$\partial_k \Gamma_{\text{reg}}^{2\text{PI}} = \frac{\delta \Gamma_{\text{reg}}^{2\text{PI}}}{\delta \Delta_k} \cdot \partial_k \Delta_k = -\frac{\hbar}{2} R_k \cdot \partial_k \Delta_k$$

by the functional chain rule.

Closure

1PI_{average}
Convexity

$$\frac{\delta^2 \Gamma^{1\text{PI}}}{\delta \phi_{x_1} \delta \phi_{x_2}} \frac{\delta^2 (-W)}{\delta J_{x_1} \delta J_{x_2}} = 1$$

implies

$$\left[\Delta_{k; x_1, x_2}^{1\text{PI}} \right]^{-1} = \frac{\delta^2 \Gamma_{\text{av}}^{1\text{PI}}}{\delta \phi_{x_1} \delta \phi_{x_2}} + R_{k; x_1, x_2}$$

2PI_{reg} [PM, Saffin '21]
Convexity

$$\text{Hess}_{\phi, \Delta^{\text{nc}}} \Gamma^{2\text{PI}} \cdot \text{Hess}_{J, -R/2} (-W) = \mathbb{1}$$

implies

$$\left[\Delta_{k; x_1, x_2} \right]^{-1} = \frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \phi_{x_1} \delta \phi_{x_2}} + R_{k; x_1, x_2}$$

$$- \frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \phi_{x_1} \delta \Delta_{k; y_1, y_2}} \left[\frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \Delta_{k; y_1, y_2} \delta \Delta_{k; y_3, y_4}} \right]^{-1} \frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \Delta_{k; y_3, y_4} \delta \phi_{x_2}}$$

[see also footnote 11 of Cornwall, Jackiw, Tomboulis '74]

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Convexity

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2PI_{reg} [PM, Saffin '21]
Convexity

$$\text{Hess}_{\phi, \Delta^{\text{nc}}} \Gamma^{2\text{PI}} \cdot \text{Hess}_{J, -R/2} (-W) = \mathbb{I}$$

implies

$$\left[\Delta_{k; x_1, x_2} \right]^{-1} = \frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \phi_{x_1} \delta \phi_{x_2}} + R_{k; x_1, x_2}$$

$$- \frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \phi_{x_1} \delta \Delta_{k; y_1, y_2}} \left[\frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \Delta_{k; y_1, y_2} \delta \Delta_{k; y_3, y_4}} \right]^{-1} \frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \Delta_{k; y_3, y_4} \delta \phi_{x_2}}$$

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2PI_{reg} [PM, Saffin '21]
Convexity

$$\text{Hess}_{\phi, \Delta^{\text{nc}}} \Gamma^{2\text{PI}} \cdot \text{Hess}_{J, -R/2} (-W) = \mathbb{1}$$

implies

$$\left[\Delta_{k; x_1, x_2} \right]^{-1} = \frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \phi_{x_1} \delta \phi_{x_2}} + R_{k; x_1, x_2}$$

$$-\frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \phi_{x_1} \delta \Delta_{k; y_1, y_2}} \left[\frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \Delta_{k; y_1, y_2} \delta \Delta_{k; y_3, y_4}} \right]^{-1} \frac{\delta^2 \Gamma^{2\text{PI}}}{\delta \Delta_{k; y_3, y_4} \delta \phi_{x_2}}$$

2PI resummation

Zero-dimensional playground [PM, Saffin '19, '21 & '22]

Take

$$S(\Phi) = \frac{1}{2}\Phi^2 + \frac{\lambda}{4!}\Phi^4$$

with $\hbar > 0$ and $\lambda > 0$.

We can calculate

$$W(J, R_k) = -\hbar \ln \int D\Phi \exp \left[-\frac{1}{\hbar} \left(S(\Phi) - J\Phi + \frac{1}{2}R_k\Phi^2 \right) \right],$$

any effective action and its n -point variables analytically to a given order in λ .

Ansätze [PM, Saffin '21]

1PI_{average}

Ansatz:

$$\Gamma_{\text{av}}^{1\text{PI}} = \alpha^{1\text{PI}}(R_k) + \frac{1}{2}\beta^{1\text{PI}}(R_k)\phi^2 + \frac{1}{4!}\gamma^{1\text{PI}}(R_k)\phi^4$$

Solve flow equations and compare with explicit result:

$$\begin{aligned}\Gamma_{\text{av}}^{1\text{PI}} &= S(\phi) + \frac{\hbar}{2} \left[\ln [\Delta^{1\text{PI}}]^{-1} \right] \\ &+ \hbar^2 \left[\frac{\lambda}{8} [\Delta^{1\text{PI}}]^2 - \frac{\lambda^2}{12} \phi^2 [\Delta^{1\text{PI}}]^3 \right] \\ &+ \hbar^3 \left[-\frac{\lambda^2}{12} [\Delta^{1\text{PI}}]^4 \right]\end{aligned}$$

2PI_{reg}

Ansatz:

$$\Gamma^{2\text{PI}} = \alpha(\Delta_k) + \frac{1}{2}\beta(\Delta_k)\phi^2 + \frac{1}{4!}\gamma(\Delta_k)\phi^4$$

Solve flow equations and compare with explicit result:

$$\begin{aligned}\Gamma^{2\text{PI}} &= S(\phi) + \frac{\hbar}{2} \left[\ln \Delta^{-1} + \left(1 + \frac{\lambda}{2}\phi^2 \right) \Delta - 1 \right] \\ &+ \hbar^2 \left[\frac{\lambda}{8}\Delta^2 - \frac{\lambda^2}{12}\phi^2\Delta^3 \right] \\ &+ \hbar^3 \left[-\frac{\lambda^2}{48}\Delta^4 \right]\end{aligned}$$

Flow equations [PM, Saffin '21]

1PI_{average}

$$\partial_k \alpha(\Delta_k) = \frac{\partial \alpha^{1\text{PI}}(R_k)}{\partial R_k} \partial_k R_k \text{ etc.}$$

Take derivatives of $[\Delta^{1\text{PI}}]^{-1}$ with respect to ϕ at $\phi = 0$ and solve for $\partial^n \{\alpha^{1\text{PI}}, \beta^{1\text{PI}}, \gamma^{1\text{PI}}\} / \partial R_k^n$:

$$\partial_k \alpha^{1\text{PI}} = \frac{\hbar}{2} \frac{\partial_k R_k}{[\beta^{1\text{PI}} + R_k]}$$

$$\partial_k \beta^{1\text{PI}} = -\frac{\hbar}{2} \frac{\gamma^{1\text{PI}} \partial_k R_k}{[\beta^{1\text{PI}} + R_k]^2}$$

$$\partial_k \gamma^{1\text{PI}} = 3\hbar \frac{[\gamma^{1\text{PI}}]^2 \partial_k R_k}{[\beta^{1\text{PI}} + R_k]^3}$$

2PI_{reg}

$$\partial_k \alpha(\Delta_k) = \frac{\partial \alpha(\Delta_k)}{\partial \Delta_k} \partial_k \Delta_k \text{ etc.}$$

Take derivatives of Δ^{-1} with respect to ϕ and Δ at $\phi = 0$ and solve for $\partial^n \{\alpha, \beta, \gamma\} / \partial \Delta_k^n$ with $R_k^0 = R_k(\phi = 0, \Delta_k)$:

$$\partial_k \alpha = \frac{\hbar}{2} R_k^0 \frac{\partial_k \beta + \partial_k R_k^0}{[\beta + R_k^0]^2}$$

$$\partial_k \beta = -\left\{ \frac{\hbar}{2} \gamma - \frac{\hbar^2}{2} \frac{\gamma^2}{[\beta + R_k^0]^2} \right\} \frac{\partial_k \beta + \partial_k R_k^0}{[\beta + R_k^0]^2}$$

$$\partial_k \gamma = \mathcal{O}(\gamma^4)$$

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$$\partial_k \alpha(\Delta_k) = \frac{\partial \alpha(\Delta_k)}{\partial \Delta_k} \partial_k \Delta_k \text{ etc.}$$

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$$\partial_k \alpha(\Delta_k) = \frac{\partial \alpha(\Delta_k)}{\partial \Delta_k} \partial_k \Delta_k \text{ etc.}$$

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$$\partial_k \alpha = \frac{\hbar}{2} R_k^0 \frac{\partial_k \beta + \partial_k R_k^0}{[\beta + R_k^0]^2}$$

$$\partial_k \beta = -\left\{ \frac{\hbar}{2} \gamma - \frac{\hbar^2}{2} \frac{\gamma^2}{[\beta + R_k^0]^2} \right\} \frac{\partial_k \beta + \partial_k R_k^0}{[\beta + R_k^0]^2}$$

$$\partial_k \gamma = \mathcal{O}(\gamma^4)$$

Vertex functions

1PI_{average}

$$\partial_k \gamma^{1\text{PI}} = 3\hbar \frac{[\gamma^{1\text{PI}}]^2 \partial_k R_k}{[\beta^{1\text{PI}} + R_k]^3}$$

n -point vertices are given by

$$\Gamma_{1\text{PI}}^{(n>2)} = - [\Delta^{1\text{PI}}]^{-n} \left\{ \Delta^{1\text{PI}} \frac{\partial}{\partial \phi} \right\}^{n-2} \Delta^{1\text{PI}}$$

giving

$$\Gamma_{1\text{PI}}^{(4)} \Big|_{\phi=0} = \gamma^{1\text{PI}}$$

2PI_{reg}

$$\partial_k \gamma = \mathcal{O}(\gamma^4)$$

n -point vertices are given by [PM, Saffin '22]

$$\Gamma^{(n>2)} = - \Delta^{-n} \left\{ \Delta \left[\frac{\partial}{\partial \phi} - \frac{\partial^2 \Gamma^{2\text{PI}}}{\partial \phi \partial \Delta} \left(\frac{\partial^2 \Gamma^{2\text{PI}}}{\partial \Delta^2} \right)^{-1} \frac{\partial}{\partial \Delta} \right] \right\}^{n-2} \Delta$$

giving

$$\Gamma^{(4)} \Big|_{\phi=0} = \gamma - \frac{3}{2} \hbar \gamma^2 \frac{1}{[\beta + R_k^0]^2}$$

Concluding remarks

- Exploit the freedom in the **2PI effective action** to fix the **two-point source** to be the **regulator**, leading to **self-consistent flow equations** that are **complementary** to the well-known ones.
- Extremization wrt the regulator involved in this approach (a) leads to the usual **2PI resummation** and (b) potentially lessens the regulator dependence.
- Many questions: e.g., can usual approximation schemes and methods, i.e., **LPA**, **derivative expansion**, **PMS**, **regulator optimisation** be applied in the same way?

Thank you for your attention.

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